

DEVELOPMENT A LOCAL SYSTEM FOR MEASURING TRACTORS PERFORMANCE

Samir M. Younis^{*} , **EL. Said R. Elashry**^{*}
Ahmed. F. Bahnasy^{**} , **Islam. M., Elsybaee**^{***}

ABSTRACT

The tractor test systems were conducted to evaluate the effect of the modified system and compared to the system used in tractor test station on the value of tractor performance. The developed device is consisted of transducer, signal conditioner and recorded unit. The hydraulic pull dynamometer, strain gage pull dynamometer, load cell, hydraulic PTO dynamometer, magnetic pickup transducers and fifth wheel were used to measure tractor parameter. Statically analysis shows that no significant between devolved device (named system 1) and the system used in tractor test station (named system2). Devolved device is expected to be a worthy one to establish reliable data of the performance parameters of tractors and implements.

INTRODUCTION

The proper selection of tractor and implement for a particular farm situation requires availability of the field performance data of both tractors and implements. Tractor and implement test are needed in different farm sites under different operating conditions to prevent serious damage. This will enable the proper selection of tractor and implement for a particular requirement.

Many of instrumentation systems are determine the field performance of tractors and implements operating under different field conditions have been developed and reported by researchers. Most of them were designed exclusively for a particular tractor and not easily adaptable to other tractors. Also most of the developed systems were used to majority parameters like drawbar pull, ground speed, and drive wheel speed. From these measurements drawbar power and wheel slip could be calculated. This is hard and expensive to instrument one tractor and take it to

* Prof. of Agric. Eng. - Faculty of Agric.- Alexandria University.

** Senior Researcher, Agric. Eng. Research Institute, Dokki, Giza, Egypt.

*** Engineer, Agric. Eng. Research Institute, Dokki, Giza, Egypt.

different farm sites to make a complete field performance data bank for the tractors and implements. So it is necessary to have simple instrumentation system easily adaptable to a wide range of agricultural tractors used in different farm sites and if any part of the instrumentation system damaged it is necessary to find another part.

Raheman and Jha (2007) was developed a microcontroller-based slip sensor for a 2WD tractor to indicate slip values during on-farm use. This sensor comprised of four components: power supply; sensing of throttle position, gear position, and wheel rpm; processing of collected data; and display unit. Power was taken from the tractor battery. Rotary potentiometer and proximity switches were installed on the tractor to measure throttle position and wheel revolution, respectively. The performance of developed slip sensor was evaluated both on tar macadam surface as well as in the field. The variations between indicated and actual slip were found to be within 0–5% for both the surfaces, thus indicating the accuracy of slip measurement by the developed slip sensor.

Mohamed et al., (2004) designed and calibrate the drawbar pin which could be used as a force transducer to measure the draft of trailed implements. This pin transducer consists of a pin on which are mounted a total of four strain gauges. This pin is used as a hitch pin and as a measuring device without changing the tractor hitch configuration. Field experiments were carried out with disk harrow at different harrowing depths. The pin transducer producer a linear out put depend end of pull force only. (Nada, 2003; Elgwadi 2005) presented a direct method of estimating tractor power by measuring torque and numbers of revolutions of the tractor power take off shaft, during operating rotating agricultural implement at actual field work.

Miszczak (2005) mentioned that there were many models describing the work of rotary tillers, including torque valuation because the torque requirement may be very important for designers, as well as for other experts applying such machines in the field operations. Strain gage load devices convert the load acting on them into electrical signals. The gages themselves are bonded on to a structural member that deforms when weight is applied. In most cases, four strain gages are used to obtain maximum sensitivity and temperature compensation. Two of the gauges

are usually in tension, two in compression and are wired with compensation adjustments. When weight or torque is applied, the strain changes the electrical resistance of the gages in proportion to the load or torque.

Elashry (2002) was used a separated apparatus for fuel consumption. It was installed and connected to tractor fuel tank through hoses and two 2-way valves. The secondary tank was first filled with fuel to the mark on the top of the tab. During the actual run, the tractor was first let go on its fuel from the main tank. To measure the fuel consumption during a specific field operation, the secondary tank was utilized through the valve (1) and (2). at the end of the run, the valves were refilled off. The secondary tank was refilled to the mark on the tube from a graduated cylinder and amount of refuel was taken as fuel consumption during the specific operation duration.

(Elashry et al., 1994; Al-Janobi et al., 1998; Nada, 2003) used the 5th wheel to measure the travel speed, it is made from a motorcycle wheel and tire with a medium knobby tread. It is connected to the tractor via spring load 4-bar linkage.

Chen et al., (2007), developed a 2D double extended octagonal ring (DEOR) drawbar dynamometer with a draft capacity of 180 kN. The two extended octagonal rings were oriented vertically on either side of the tractor drawbar which provided a better match of strain to expected drawbar draft and vertical load than could be achieved with a horizontal orientation in previous designs.

Sahu and Raheman (2008) used A decision support system (DSS) was developed in Visual Basic 6.0 programming language for matching tillage implements with 2WD tractors and for predicting the field performance of the tractor-implement system. The DSS was validated with the data collected from the field experiments conducted with a 31 kW PTO power 2WD tractor and three tillage implements (2–30 cm moldboard plow, 7-7 disks (1.6 m) offset-disk harrow and 9–23 cm field cultivator) under different soil and operating conditions. It was found that the DSS on an average under-predicted the draft and slip values by 10.2 and 15.6%, respectively, while it over-predicted the actual field capacity by 2.5% from the observed values.

The objectives of this search were to:

- Construct and calibrate local system simple and cheap to measure the field performance such as P.T.o torque, drawbar pull travel speed, fuel consumption and (fuel, oil and cooling) temperature.
- Designe strain gage pull dynamometer to measure tractor drawbar pull.
- Constructing load cell transducer to measure the vertical force which applied to the torque with PTO dynamometer arm.

MATERIALS AND METHODS

Tractor test main elements

Any measuring system should be consisting of necessary elements such as 1-transducer 2- signal conditioner 3- recorder or indicator.

1- The transducer:

The transducer is an energy converter which receives the physical quantity being measured and converts it in to some other physical variable; e.g. flow to pressure, speed to voltage, strain to resistance. The transducer is undoubted the weakest link in the measuring chain, for the measured quantity is always modified by the presence of the transducers, making a perfect measurement theoretically impossible. This" loading" effect can by minimized by the design and installation of the transducer, but it is always present to some degree.

2-The signal conditioner:

The signal conditioner rearranges the transuded signal to a form which can be readily recorded or monitored.

3-The recorder or display:

The recorder or display is the recorder, display, or indicating device. Many recorders have a transuding action at their followed by some further signal conditioning.

Tractor test measurements are fuel consumption, draft or drawbar pulls ground speed, fuel, oil and cool temperature and slip ratio.

A-Fuel apparatus

A separate apparatus was used to measure fuel consumption. It consisted of a secondary tank of 4.5 liters capacity with a level marked tube and bulb with volume 127.4 cm³.

B-Strain gage pull dynamometer

Strain gage pull dynamometer was designed and constructed at tractor test station. The objective of construction this drawbar force transducer is to measure the draft of the tractor under test on the concrete road and field test from which the power requirements can be determined. Basically the pull transducer was constructed by machining down a middle section of a G10180 (1.5 x1.9 cm) hot-rolled (HR) steel. The anticipate stresses were calculated for maximum tractor intended for this design which tractor is used. The transducer dimension was (24 x1.9 cm) and was machining down to (1.5x1.9 cm) in cross section at the point where the gages are mounted. The strain gage pull dynamometer is illustrated in Figure (1).

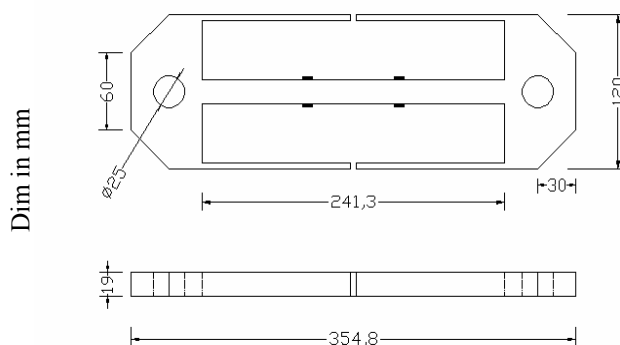


Figure (1): The strain gages pull dynamometer.

C-Strain gage indicator

The strain gage indicator is portable, battery powered precision instrument for use with resistive strain gages and transducers. The strain gage indicator accepts full, half, or quarter bridge.

D-Modified System Description

Construction of the developed device was installed at the Testing and Research Station for Tractors and Farm Machinery, Alexandria Governorate. The modified system had stages and a lot of components .it is consist of amplifier circuit, digital multimeter and computer. Modified system used to measure drawbar pull, PTO torque, rotational speed, ground speed, oil temperature, cooling temperature and fuel temperature.

E-Strain gage load cell

The objective of constructing this load cell transducer is to measure the vertical force which applied to do torque with PTO dynamometer arm from which the power requirements can be determined basically the load

cell was constructed by machining down of middle section of a G10180 (20 mm × 11 mm) hot-rolled (HR) steel the anticipation stresses were calculated for maximum tractor intended for this design. The transducer dimension was 15.5 cm x 8 cm and was machined down to (20 mm x 11 mm) in cross section at the point where the gages are mounted. The strain –gage load cell design is illustrated in Figure (2).

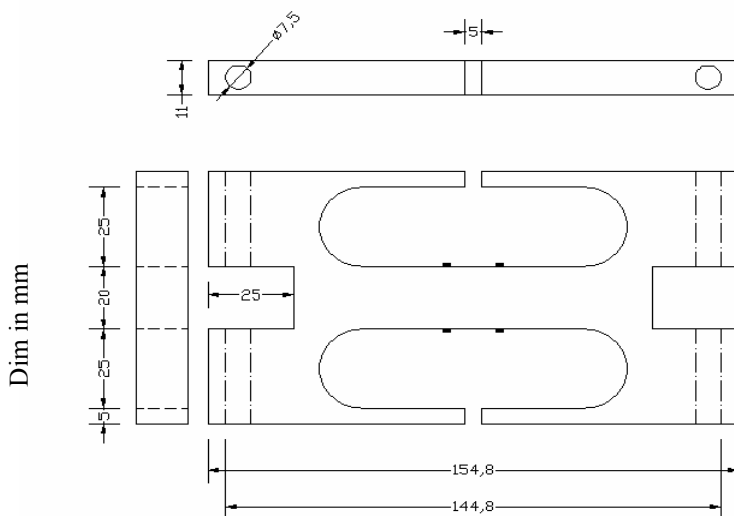


Figure (2): The strain gage load cell

F-Hydraulic drawbar dynamometer.

For agricultural work hydraulic drawbar dynamometer are widely used. The pressure set up in the fluid contained in a hydraulic link is transmitted to a small recording cylinder, in which a plunger acts against the force of a spring. The movement of the plunger may be read directly, the hydraulic drawbar dynamometer was used to calibrate the strain gage pull dynamometer. The hydraulic drawbar dynamometer capacity is 8000 kg. Its indicator was analog but it had liquid in his indicator box to reduce the movement of the indicator when any one wants to read any values.

Specifications of tractors

Three tractors used in this study and numbered from 1 to 3. Tractors No (1) and (2) were used as loading tractors the other was used for testing the instrumented trailed under study. The three tractors specifications are tabulated in Table (1).

Table (1): Specifications of tractors

specifications	Tractor No(1)	Tractor No(2)	Tractor No(3)
Make	U.S.A	U.S.A	-----
Model	John Deere	John Deere	-----
Number of driving wheel	4 x 4	4 x 4	4 x 4
Engine			
Model	6076 TRW04	6076 TRW08	-----
Type	Diesel	Diesel	Diesel
Cylinders	6 (Vertical)	6 (Vertical)	6 (Vertical)
Bore x stroke	115.8 X 120.7	115.8 X 120.7	
Cubic capacity	7634 cc	7634 cc	7500 cc
Fuel system			
Feed system	In-line	In-line	In-line
Fuel tank capacity	246 liters	246 liters	220 liters
Rated engine Power	88 kW at 2200 rpm	80 kW at 2200 rpm	120 kW at 2100 rpm
Cooling system			
Type of coolant	Water	Water	Water
Power take off			
Type	Independent	Independent	Independent
Actuation	Electro hydraulic, gradual, operator controlled	Electro hydraulic, gradual, operator controlled	Electro hydraulic, gradual, operator controlled
Speed	540 /1000 rpm	540 /1000 rpm	540 /1000 rpm
Tractor Dimensions			
Length (mm)	4023	4027	4266
Width (mm)	2438	2870	2523
Height (mm)	2959	3173	2989
Wheel base	2676	2675	2723
Tractor weight			
Total (kg)	6415	6329	6300

Measurement

The measurements required to determine tractor performance are fuel consumption, drawbar pull, PTO torque, ground speed, rotational speed, slip and (fuel, oil and cool temperature).

1-Fuel consumption

A separate apparatus was used to measure fuel consumption. It consisted of a secondary tank of 4.5 liters capacity with a level marked tube and bulb with volume 127.4 cm³. The apparatus was installed and connected to the tractor fuel Tank through hoses and two valves. The secondary tank was first filled with fuel during the actual run. The tractor was first let go

on its fuel from the main tank .to measure the fuel consumption during a specific field operation, the secondary tank was utilized through the valves to fill the bulb. Then, turn the valves off and used stop watch when the fuel arrived to the first mark of the bulb. After that when the fuel arrives to the second mark. Turn off the stop watch at the same time. The bulb had constant volume, so it's easy to calculate the fuel consumption. this system used to measuring fuel consumption with the nine gears when measured the drawbar power and measuring fuel consumption at PTO power.

2-Drawbar pull

Two methods used to measure the drawbar pull. Drawbar pull measured using strain gage pull dynamometer. The calibrated hydraulic dynamometer (5 ton capacity) at faculty of engineering Alexandria University was to calibrate the pull meter strain gage. The strain gage pull meter was connected with new instrument or strain indicator to calibrate the strain gage pull meter. An applied in equal steps from no load to the maximum allowed load and then reduced load approximately in the same steps back to no load.

3-Tractor PTO torque

The PTO hydraulic dynamometer used to measure the PTO torque and PTO (r.p.m) to determine PTO power. Two methods used to measure the PTO torque.

First method the developed used device with load cell used to measure the torque. A known torque was applied to the transducers. The value of the known load was read with new instrument. A known torque was applied from no load to the maximum allowed torque. Load cell transducers were excited by a stabilized dc volt supply with input battery (9) volt .the new instrument read the volt with the same torque. The second method the same procedures was followed with the strain meter.

4- Ground speed

Two methods used to measure the ground speed, using fifth wheel and the traditional method. The first method is the true ground speed is measured using a 5th wheel. It mounted on a tool bar directly behind the right front wheel. The fifth wheel can be positioned on the tool bar so that it either follows in the track made by the front tractor wheel or rolls on

undisturbed soil. This flexibility is useful since on rough, bumpy ground it may be preferable to operate in the wheel track, but on smooth ground it may be better to run on undisturbed. The 5th wheel was made from a motorcycle wheel and tire with a medium knobby tread. It is connected to the tractor via a spring load 4-bar linkage. A magnetic pick-up mounted to the vertical bar senses the rotation of a toothed gear with 120 –tooth gear was attached to the 5th wheel with this arrangement the magnetic pick-up can move vertically but cannot rotate as the 5th wheel moves up must sense only 5th wheel rotation. The signal comes from magnetic pickup goes directly to the modified system. Figure (3) shows the fifth wheel mechanism.

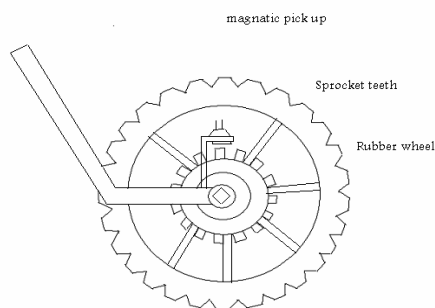


Figure (3): The fifth wheel mechanism

5- P.T.O rotational speed

The number of revolutions of land engaging wheels on tractors and machines test rigs and in the field and pedals and handles of machines such as small threshers, grinders and water pumps, can be counted by eye. For shafts turning at higher speeds, some form of counting apparatus is required. For high rotational speed there are two methods to measure it. The first method is mechanical revolution counters and totalizes will require time to be measured by stop watch. Electrical and electronic units automatically count the number of revolutions over a period of time and the results are displayed and continually updated. This unit used with PTO hydraulic dynamometer. The second method is used a new instrument with a magnetic pick up to calculate the number of revolution by calibrating the new instrument. The wheel speed transducer was illustrating in Figure (4).

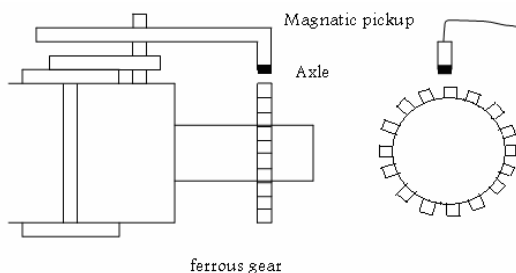


Figure (4): The rotational speed transducer

6-Fuel, oil and cool temperatures

The digital multimeter used to measure temperature. The DT92 Advanced series digital multimeter is a compact precision and battery operated.

7- Slip ratio

Slip is defined as the relative movement in the direction of travel at the traction device-soil interface. It is generally expressed as:

$$S = 1 - \frac{V_a}{V_t}$$

Where:

S = wheel slip (-)

V_a = actual travel speed

V_t = theoretical wheel speed = $r \times \omega$

ω = angular velocity of wheel (1/sec)

r = actual rolling radius of wheel on hard surface (m)

A simple methods of determining the a mount of wheel slip is to make a mark on the tractor drive wheel with colored tapes and a known distance the tractor moves forward is measured, 10 revolution under no load (A) and on the same surface and with the same number of revolutions with load (B). Pins adequate length will used for making on the field.

$$\text{Percentage of wheel slip} = \frac{A - B}{A} \times 100$$

The calibration of the rational speed was made in the lab of tractor test station by applying a known rational speed in equal steps from no speed to the maximum allowed speed and then reduced in approximately the same steps back to no speed; sprocket with magnetic pickup was used, with 60 teeth. The sprocket was used to measure the RPM of the PTO of the tractor during the PTO test of the tractor.

The following equation represent the calibration data.

$$Y = 0.0008X + 0.0667$$

Where:

Y = device reading mv;

X = Rotation speed, rpm

Calibrations

1- Strain gage pull dynamometer calibration

The pull dynamometer was attached to a steel column which was fixed to a tractor. The calibrated hydraulic dynamometer was attached in series with the pull meter strain gage. The load was applied to the transducer using a pre-calibration unit; the pull meter was connected with new instrument and/ or strain indicator, the same procedure from no load to the maximum allowed load is followed. The calibration equation between hydraulic and strain gage dynamometer can be expressed as follows:

$$Y = 0.2121 X$$

Y = value of strain gage dynamometer, kN

X = Value of hydraulic dynamometer, kN

2- Calibrating the hydraulic (PTO) dynamometer

1. Turn knob counter clockwise to open valve on hand pump to relieve hydraulic pressure in recording cylinder.
2. Locate sliding button at 12 inch torque mark on torque arm bar. Position recording cylinder directly under sliding button and lock cylinder in place.
3. Position test bar torque arm. Align mark on test bar with 12 inch mark on scale of torque arm bar.
4. To charge recording cylinder. Close valve on hand pump. Then operate hand pump so that torque arm does not contact either torque arm stops.
5. Hang a known weight from the 4 foot mark near the end of the feet bar. If adding weight causes torque arm to touch torque arm stop.
6. Read inner (kW) scale .Multiply reading by ten to obtain (N.m)

3- Load cell calibration

Torque was recoded with new instrument and/or strain indicator. A known torque was applied from no load to the maximum allowed torque and then reduced in approximately the same steps back to no load. Load cell transducers were exited by a stabilized dc volt supply with input

battery (9) Volt .the new instrument read the volt with the same torque and strain indicator read the torque with the same strain or mV.

The following equation expressed the relationship between applied torque and the development instrument and strain meter device:

$$Y_1 = 0.3845X_1$$

Where:-

Y_1 = new instrument reading, mv;

X_1 = applied torque kN

4-Fifth wheel calibration

The fifth wheel was calibrated at concrete road a known forward speed in equal steps from no speed to the maximum allowed speed, and then reduced in approximately the same steps back to no speed, with magnetic pickup with 120 tooth sprockets. The following equation represents the calibration data by using the fifth wheel.

$$Y = 0.63X$$

Where:

Y = Device reading, mv

X = Forward speed, km/hr

RESULT AND DISCUSSION

1- Drawbar performance test

The governor control lever shall be sit for maximum power at rated engine speed. In case of part- time 4WD, tests shall be performed under 4WD condition.

$$\text{Drawbarpower(kW)} = \frac{\text{Drawbar pull(N)} \times \text{travelingspeed(km/hr)}}{3600}$$

The tests at the drawbar shall be conducted according to the following regulations in order to provide reasonably comparable results in all countries. For tractors with pneumatic tires, the tests shall be carried out on a clean, horizontal, dry concrete or tar macadam surface containing a minimum number of joints. Tests of steel –wheeled tractors and track-laying tractors shall be carried out on flat, dry, horizontal, mown or grazed grassland, or on a horizontal track having equally good adhesion characteristics: A moving track (treadmill) may also be used subject to the conditions that results produced are comparable to those obtained on

the surface mentioned above. The type of track test shall be clearly stated in the report.

2-PTO performance test

The PTO speed, torque and fuel consumption were recorded. Measuring was done on the steps starting from min engine speed to max engine speed. The shafts connecting the PTO to the dynamometer shall not have any appreciable angularity at the universal joint. The temperature of the atmosphere shall be 23 ± 7 °c.

$$\text{PTO power(kW)} = \frac{2\pi NT}{60}$$

T=Torque (Newton. m)

N = revolution (rpm)

$$\text{S.f.c.} = \frac{F}{\text{PTO Power}} \times G$$

S.f.c = Specific fuel consumption (kg/kW.hr)

F: Fuel specific gravity (kg/m³)

The statistical analysis in Table (2) showed the T test of torque and power for different systems during the PTO test that, there was no significant different between system1 and system 2. Fuel temperature ranged between 45-46 °C, Oil temperature ranged between 95-97°C and Cool temperature was 81°C.

Table (2): The statistical analysis of PTO test for system 1 and system2

	SYSTEM 1		SYSTEM 2	
	torque (N.m)	power (kW)	torque (N.m)	power (kW)
average	494	92	496	93
No. of reading	26	26	26	26
Max. value	635	116	634	118
Median value	579	109	579	109
Min. value	0	0	0	0
T cal,	0.98041		0.94194422	
T table	2.009		2.009	

Fig.(5, 6) show the relationship between engine speed , fuel consumption, specific fuel consumption, PTO torque and PTO power for the two systems under study. The maximum value of PTO torque found at low engine speed of (1310and1300 rpm) of 635 and 634 kN.m for system 1 and system

2 respectively. The maximum value of PTO power found at engine speed of (2041 and 2036) of 116 and 118 kW for system 1 and system 2 respectively.

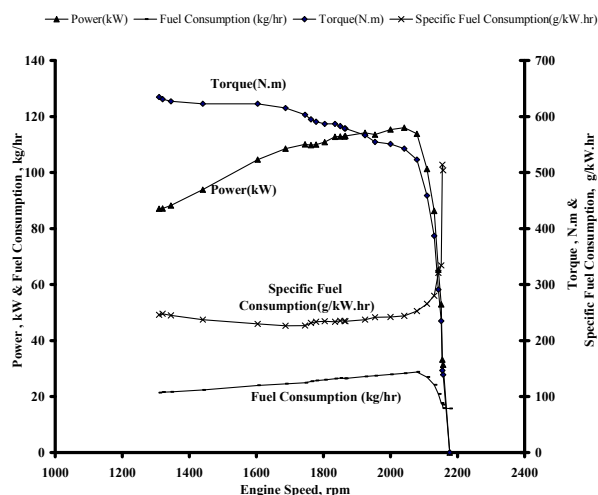


Figure (5): PTO performance of tractor using system1

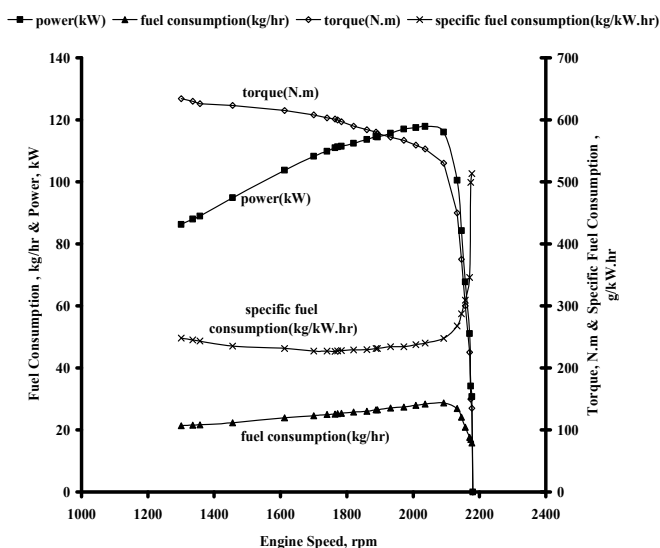


Figure (6): PTO performance of tractor using system2

3- Effect of tractor forward speed on tractor performance:

The performance of drawbar test has been measured the following data: Forward speed, Fuel consumption (kg/hr). The calculated data was the drawbar power (kW), equivalent forward speed and Drawbar Pull. Figs (8, and 9) demonstrate the performance of the tractor in drawbar test for

systems 1 and 2 at two levels of speed (6gears was at low level speed and 3gears at high level speed). Table (4) showed that the maximum drawbar power affected by drawbar pull using system 1 for gears (6th low gear, 3rd high gear). The maximum value of Drawbar Power found at the lowest drawbar pull of (33.4 and 30.3 kN) of 62.25 and 65.16 kW and at the highest forward speed of (6.7 and 7.75 km/hr) for system 1 respectively. The minimum value of drawbar power found at highest drawbar pull using system 1 for gears (1st low, 2nd low) of (50.8 and 49 kN)of 14.59and 23.95 kW and at the lowest forward speed of (1.03 and 1.76 km/hr) for system 1 respectively.

Table (4) showed that the maximum drawbar power affected by drawbar pull using system 2 for gears (6th low gear, 3rd high gear). The maximum value of Drawbar Power found at the lowest drawbar pull of (33.5 and 29.1 kN) of 62.58 and 62.31 kW and at the highest forward speed of (6.72 and 7.7 km/hr) for system 2 respectively.

Table (3): the data of drawbar pull measured using improved system1

	Gear low						Gear high		
	1st	2nd	3rd	4th	5th	6th	7th	8th	9th
Drawbar Pull at max power, kN	49	47.4	44.4	43.3	36.2	33.4	40.2	34.6	30.3
Speed at Max Drawbar Power, km/h	1.77	2.31	2.94	3.89	4.91	6.7	4.84	5.77	7.75
Slip at Max Drawbar Power, %	12.19	9.7	10.8	7.8	10.1	7.7	7.9	8.9	5.3
Max Drawbar Power, kW	24.04	30.42	36.3	46.79	49.43	62.25	50.05	55.45	65.16
Fuel consumption at Max Drawbar Power, kg/h	18.97	18.8	18.6	17.84	18.91	18.1	18.5	19.29	17.2
Specific fuel consumption at Max Drawbar Power, g/kW.h	0.79	0.62	0.51	0.38	0.38	0.29	0.37	0.35	0.26
Min specific fuel consumption, g/kW.h	0.75	0.6	0.5	0.38	0.37	0.28	0.37	0.34	0.26
Slip at Min specific fuel consumption, %	7.78	6.7	7	7.8	13.2	10.2	7.9	5.6	7.7
Fuel consumption Min specific fuel consumption	15.71	16.84	17.47	17.84	18.29	17.4	18.5	17.6	16.8
Drawbar Power at Min specific fuel consumption, kg/h	20.87	27.78	35.08	46.79	49.22	61.27	50.05	51.71	64.69
Speed at Min specific fuel consumption, km/h	1.85	2.39	3.11	3.89	4.74	6.52	4.84	5.99	7.56
Drawbar Pull at Min specific fuel consumption, kN	40.5	42	40.6	43.3	37.4	33.8	40.2	31.1	30.8

Table (4): the data of drawbar pull measured using system (2).

	Gear low						Gear high		
	1 st	2 nd	3 rd	4 th	5 th	6 th	7 th	8 th	9 th
Drawbar Pull at max power, kN	48.9	46.5	43.7	43.2	36.8	33.5	40	34.8	29.1
Speed at Max Drawbar Power, km/h	1.77	2.31	2.94	3.9	4.9	6.72	4.94	5.9	7.7
Slip at Max Drawbar Power, %	11.83	9.44	11.99	8.42	10.61	7.94	7.8	6.76	7.8
Max Drawbar Power, kW	24.05	29.8	35.67	46.84	50.09	62.58	49.84	57.09	62.31
Fuel consumption at Max Drawbar Power, kg/h	18.97	18.8	18.66	17.84	18.2	18.4	18.5	19.22	18.8
Specific fuel consumption at Max Drawbar Power, g/kW.h	0.79	0.63	0.52	0.38	0.36	0.29	0.37	0.34	0.3
Min specific fuel consumption, g/kW.h	0.75	0.61	0.5	0.38	0.36	0.28	0.37	0.34	0.28
Slip at Min specific fuel consumption, %	7.85	6.2	5.97	8.42	10.6	10.6	7.8	4.97	13.7
Fuel consumption Min specific fuel consumption	15.71	16.55	16.9	17.84	18.2	17.3	18.5	18.6	16.8
Drawbar Power at Min specific fuel consumption, kg/h	20.85	27.1	33.59	46.84	50.09	61.6	49.84	53.47	6.27
Speed at Min specific fuel consumption, km/h	1.85	2.39	3.15	3.90	4.9	6.52	4.94	6.02	7.21
Drawbar Pull at Min specific fuel consumption, kN	40.5	40.8	38.4	43.2	36.8	34	40	32	30

The minimum value of drawbar power found at highest drawbar pull using system 2 for gears (1st low, 2nd low) of (50.8 and 48.9 kN) of 14.46 and 23.94 kW and at the lowest forward speed of (1.02 and 1.76 km/hr)for system 2 respectively.

4- Maximum power and maximum pull

Table (5) shows the maximum power and maximum pull for system 1 and 2 . Figures 8 and 9 show the data for the two systems. The maximum drawbar power affected by drawbar pull using system 2 and system 1 for gears (6th low gear, 3rd high gear). The maximum value of Drawbar Power found at the lowest drawbar pull of (33.5 and 29.1 kN.m) of 62.58 and 62.31 kW and at the highest forward speed of (6.72 and 7.7 km/hr)for

system 2 and (33.4 and 30.3kN.m)of 62.25and 65.16 kW and at the highest forward speed of (6.7 and 7.75 km/hr) for system 1 respectively. The minimum value of drawbar power found at highest drawbar pull using system 2 and system 1 for gears (1st, 2nd). of (50.8and48.9kN.m) of

Table (5): Maximum power and Maximum Pull results

		system 2			system 1		
		Max Power, kW	Pull, kN	Speed, km/hr	Max Power, kW	Pull, kN	Speed, km/hr
Gear high	1st	24.05	48.9	1.77	24.04	49	1.77
	2nd	29.8	46.5	2.31	30.42	47.4	2.31
	3rd	35.67	43.7	2.94	36.3	44.4	2.94
	4th	46.84	43.2	3.9	46.79	43.3	3.89
	5th	50.09	36.8	4.9	49.22	37.4	4.74
	6th	62.52	33.5	6.72	62.25	33.4	6.7
Gear low	7th	49.84	40	4.49	50.05	40.2	4.48
	8th	57.09	34.8	5.9	55.45	34.6	5.77
	9th	62.31	29.1	7.7	65.16	30.3	7.75

		Max Pull , kN	Power, kW	Speed, km/hr	Max Pull, kN	Power, kW	Speed, km/hr
	1st	50.8	14.46	1.02	30.42	14.59	1.03
	2nd	48.9	23.94	1.76	49	23.95	1.76
	3rd	45.4	27.07	2.15	45.4	27.35	2.17
	4th	43.9	29.41	2.41	43.8	29.29	2.41
	5th	38.1	32.37	3.06	38.6	32.75	3.05
	6th	34.3	47.36	4.97	34.2	47.15	4.96
	7th	41.6	28.6	2.47	41.5	28.42	2.46
	8th	36.7	33.57	3.29	36.5	33.24	3.27
	9th	30	56.41	6.77	31.6	59.33	6.77

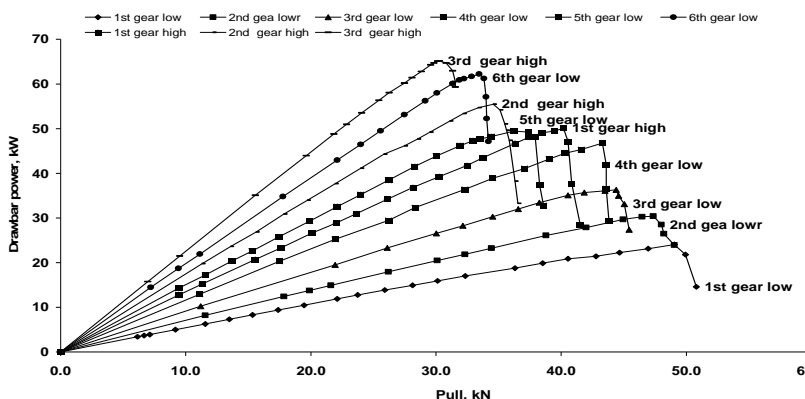


Figure (7): Drawbar power for different tractor gear using system 1.

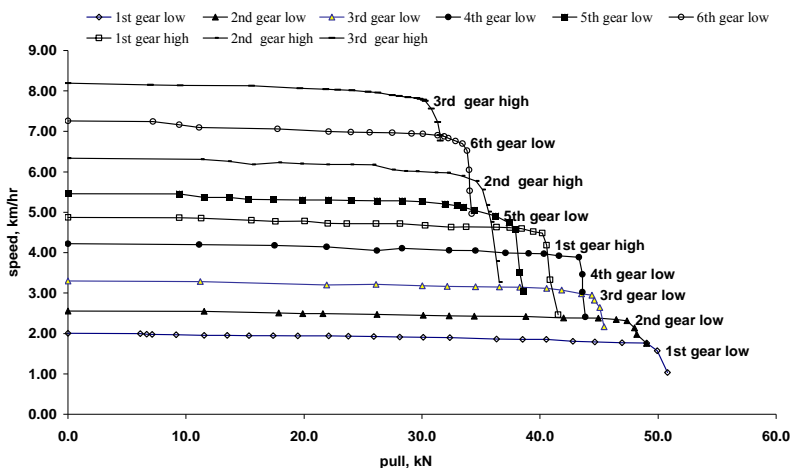


Figure (8):Tractor forward speed recorded by system 1

14.46 and 23.94 kW and at the lowest forward speed of (1.02 and 1.76 km/hr)for system 2 and (50.8 and 49kN.m)of 14.59and 23.95 kW and at the lowest forward speed of (1.03 and 1.76 km/hr) for system 1 respectively.

CONCLUSION

- The preliminary data show that no significant between the modified system (system 1) and the system used in tractor test station (system2).
- The modified system is expected to be a worthy one to establish reliable data of the performance parameters of tractors and implements.

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الملخص العربي

تطوير نظام محلي لقياس أداء الجرارات الزراعية

سمير محمد يونس* السعيد رمضان العشرى* أحمد محمد فوزى بهنسى**
اسلام محمد السيد السباعي***

إن الهدف الأساسي لهذه الدراسة هو تطوير واختبار منظومة أجهزه لقياس أداء الجرارات الزراعية ومقارنتها بالنظام المستخدم في اختبار الجرارات. الهدف الثانوي هو تطوير وتصميم جهاز لقياس الشد على قضيب يعمل بمقاييس الإجهاد والانفعال (strain gage) اجري هذا البحث في محطة أبحاث و اختبارات الجرارات والآلات الزراعية التابعة لمعهد بحوث الهندسة الزراعية بالصباحية – الإسكندرية. حيث تم استخدام نظامين من الأجهزة لقياس أداء الجرارات الزراعية احدهما معدل والأخر مستخدم حاليا . استخدم ثلاثة جرارات. احد هذه الجرارات تم اختباره واستخدم الجاران الأخران في عملية الاختبار (للتحميل). تم معايرة جهاز قياس القوة على قضيب الشد قوة وجهاز قياس القدرة على عمود الإدارة الخلفي مع قياس معدل استهلاك

* أستاذ الهندسة الزراعية – كلية الزراعة – جامعة الإسكندرية

** باحث أول معهد بحوث الهندسة الزراعية - مركز بحوث الزراعية

*** مهندس معهد بحوث الهندسة الزراعية - مركز بحوث الزراعية

الوقود وقياس عدد لفات عمود الاداره الخلفى.. وكذلك قياس درجة حرارة مياه التبريد والزيت والوقود باستخدام الثرموكابل. وقياس السرعة الامامية للجرار أثناء اختبار قضيب الشد عند 9 سرعات. بواسطة العجلة الخامسة. قياس القدرة على عمود الإدارة بجهاز اختبار القدرة على عمود الإدارة الخلفى بواسطة خلية تحميل ليتناسب مع الاجهزه الالكترونية.

النتائج المتحصل عليها من هذه الدراسة تم تلخيصها كما يلي:

1. النظام المعدل والمكون من (Computer و Digital multimeter و Amplifier circuit) مع جهاز قياس عدد لفات عمود الإدارة الخلفى و جهاز قياس معدل استهلاك الوقود و جهاز اختبار القدرة على عمود الإدارة الخلفى بالمقارنة بالنظام المستخدم فى اختبار القدرة على عمود الإدارة الخلفى انه لا توجد بينهم اى فروق معنوية.
2. لا توجد بين النظامين اى فروق معنويه بين النظام المعدل مع جهاز قياس السرعة الاماميه للجرار و جهاز قياس الشد على قضيب الشد و جهاز قياس معدل استهلاك الوقود بالمقارنة بالنظام المستخدم فى اختبار الشد على قضيب الشد.